

## Immersion - definition\*

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### 1. DEFINITION

We work in a fixed category CAT of topological, piecewise linear,  $C^r$ -differentiable ( $1 \leq r \leq \infty$ ) or real analytic manifolds (second countable, Hausdorff, without boundary) and maps between them.  $\mathring{B}^k$  denotes the open unit ball in  $\mathbb{R}^k$ ,  $k = 0, 1, \dots$ .

Let  $f: M^m \rightarrow N^n$  be such a map between manifolds of the indicated dimensions  $m \leq n$ .

**Definition 1.1.**  $f$  is a *local immersion at a point*  $x \in M$  if there exist open neighbourhoods  $U$  of  $x$  and  $V$  of  $f(x)$  in  $M$  and  $N$ , resp., such that  $f(U) \subset V$  and:

- (1) there is a CAT-isomorphism  $h: V \rightarrow \mathring{B}^n$  (i.e. both  $h$  and  $h^{-1}$  are CAT-maps) which maps  $f(U)$  onto  $\mathring{B}^n \cap (\mathbb{R}^m \times \{0\}) = \mathring{B}^m$ ; and
- (2)  $h \circ f$  yields a CAT-isomorphism from  $U$  onto  $\mathring{B}^m$ .

We call  $f$  an *immersion* (and we write  $f: M \looparrowright N$ ) if  $f$  is a local immersion at every point  $x \in M$ .

Thus an immersion looks locally like the inclusion  $\mathbb{R}^m \subset \mathbb{R}^n$  of Euclidean spaces. It allows us to visualize a given manifold  $M$  in a possibly more familiar setting such as  $N = \mathbb{R}^n$ . E.g. the projective plane  $\mathbb{R}P^2$  can be visualized in  $\mathbb{R}^3$  with the help of the *Boy's surface*, the image of a  $C^\infty$ -immersion: see for example the page on surfaces. The following two questions play an important role.

- (1) *Existence:* Given  $M$  and  $N$ , is there any immersion  $M \looparrowright N$  at all?
- (2) *Classification:* How many *essentially different* immersions exist?

### 2. THE SMOOTH CASE

This section is about the category of smooth, i.e.  $C^\infty$ , manifolds and maps. It follows from the inverse function theorem that a smooth map  $f: M \rightarrow N$  between smooth manifolds is a local immersion at  $x \in M$  precisely if the tangent map  $(Tf)_x: T_x M \rightarrow T_{f(x)}(N)$  is injective. Thus  $f$  is a smooth immersion if and only if it induces a vector bundle *monomorphism*  $Tf: TM \rightarrow TN$ . E.g. the figure  $\heartsuit$  cannot be the image of a smooth immersion, due to the two sharp corners which don't allow a well-defined tangent line. However there exists a smooth immersion  $f: S^1 \looparrowright \mathbb{R}^2$  with image the figure  $\infty$ .

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\*Atlas page : [www.map.mpim-bonn.mpg.de/Immersion](http://www.map.mpim-bonn.mpg.de/Immersion)

**Theorem 2.1.** [4, Remark], [7], *Phillips 1967* If (i)  $m < n$ , or if (ii)  $M$  is open and  $m = n$ , then the map

$$(2) \quad T : \text{Imm}(M, N) \rightarrow \text{Mono}(TM, TN), \quad f \rightarrow Tf,$$

is a weak homotopy equivalence. Here the space,  $\text{Imm}(M, N)$ , of all smooth immersions  $f : M \looparrowright N$  and  $\text{Mono}(TM, TN)$ , the space of all vector bundle monomorphisms  $\varphi : TM \rightarrow TN$ , are endowed respectively with the  $C^\infty$ -topology and the compact-open topology.

**Remark 2.3.** For a good exposition of Theorem 2.1 see [1, pp.87 and 93].

**Corollary 2.4.** Under the assumptions of theorem 2.1 there exists an immersion  $f : M \looparrowright N$  if and only if there is a vector bundle monomorphism from the tangent bundle  $TM$  of  $M$  to  $TN$ . E. g. if  $M$  is parallelizable (i. e.  $TM \cong M \times \mathbb{R}^m$ ) then  $M \looparrowright \mathbb{R}^{m+1}$ .

**Theorem 2.5.** [10, Remark] If  $m \geq 2$  then there exists an immersion  $M^m \looparrowright \mathbb{R}^{2m-1}$  (E. g. any surface can be immersed into  $\mathbb{R}^3$ ).

**Remark 2.6.** See also e.g. [1, p. 86ff].

Theorem 2.5 is best possible as long as we put no restrictions on  $M$ .

**Example 2.7.** The real projective space  $\mathbb{R}P^m$  cannot be immersed into  $\mathbb{R}^{2m-2}$  if  $m = 2^k$ . This follows from an easy calculation using Stiefel-Whitney classes: see, [6, Theorem 4,8].

**Definition 2.8.** Two immersions  $f, g : M \looparrowright N$  are *regularly homotopic* if there exists a *smooth map*  $F : M \times I \rightarrow N$  which with  $f_t(x) := F(x, t)$  satisfies the following:

- (1)  $f_0 = f, \quad f_1 = g;$
- (2)  $f_t$  is a immersion for all  $t \in I$ .

**Corollary 2.9.** Assume  $m < n$ . Two immersions  $f, g : M \looparrowright N$  are regularly homotopic if and only if their tangent maps  $Tf, Tg : TM \rightarrow TN$  are homotopic through vector bundle monomorphisms.

**Example 2.10** ( $M = S^m, N = \mathbb{R}^n$ , [7]). The regular homotopy classes of immersions  $f : S^m \looparrowright \mathbb{R}^n$ ,  $m < n$ , are in one-to-one correspondance with the elements of the homotopy group  $\pi_m(V_{n,m})$ , where  $V_{n,m}$  is the Stiefel manifold of  $m$ -frames in  $\mathbb{R}^n$ . In particular, all immersions  $S^2 \looparrowright \mathbb{R}^3$  are regularly homotopic (since  $\pi_2(V_{3,2}) = 0$ ). E. g. the standard inclusion  $f_0 : S^2 \subset \mathbb{R}^3$  is regularly homotopic to  $-f_0$ ; i. e. you can 'turn the sphere inside out' in  $\mathbb{R}^3$ , with possible self-intersections but without creating any crease.

**Remark 2.11.** The Smale-Hirsch theorem makes existence and classification problems accessible to standard methods of algebraic topology such as classical obstruction theorem (cf. e.g. [9]), characteristic classes (cf. e.g. [6]), Postnikov towers, the singularity method (cf. e.g. [5]) etc.: see [8] for the state of the art in 1963.

## 3. SELF INTERSECTIONS

It is a characteristic feature of immersions - as compared to embeddings - that  $r$ -tuple selfintersections may occur for some  $r \geq 2$ , i. e. points in  $N$  which are the image of at least  $r$  distinct elements of  $M$  (e. g. the double point in the figure 8 immersion  $f : S^1 \looparrowright \mathbb{R}^2$  with image  $\infty$ ). Generically the locus of  $r$ -tuple points of a smooth immersion  $f : M^m \looparrowright N^n$  is an immersed  $(n - r(n - m))$ -dimensional manifold in  $N$ . Its properties may yield a variety of interesting invariants which link immersions to other concepts of topology. E. g. let  $\theta(f)$  denote the mod 2 number of  $(n + 1)$ -tuple points of a selftransverse immersion  $f : M^n \looparrowright \mathbb{R}^{n+1}$ .

**Theorem 3.1.** [2] *Given a natural number  $n \equiv 1(4)$ , there is an  $n$ -dimensional closed smooth manifold  $M^n$  and an immersion  $f : M^n \looparrowright \mathbb{R}^{n+1}$  satisfying  $\theta(f) = 1$  if and only if there exists a framed  $(n + 1)$ -dimensional manifold with Kervaire invariant 1.*

According to [3] (and previous authors) this holds precisely when  $n = 1, 5, 13, 29, 61$  or possibly 125. If  $n \neq 1$  and  $n = 1(4)$  the manifold  $M$  in question cannot be orientable (cf. [2]). Thus the figure 8 immersion  $f : S^1 \looparrowright \mathbb{R}^2$  plays a rather special role here.

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